**Requirement analysis**

**A humanoid robot with human movement of the arms and movement of the feet based on the movement of wheels with a retrograde control system for balance and a special computer vision system and a robotic conversation system based on deep learning and neural networks with a system to change the type of conversations and a system to stop it remotely in case of emergency**

**Design**



**Testing**

**We place the cover installed on the legs of the robot on the cylinder that simulates flat terrain and obstacles**

